

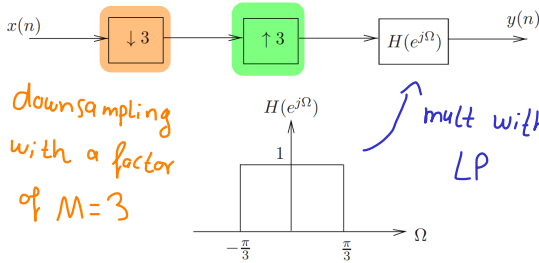
ADSP - Ex. 10

Problem 15 (Multirate Digital Signal Processing)

Consider the system shown in the figure. For each of the following input signals $x(n)$, indicate whether the output $y(n) = x(n)$.

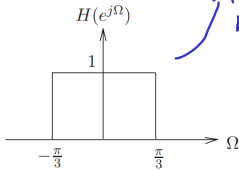
- (a) $x(n) = \cos(\pi n/4)$
- (b) $x(n) = \cos(\pi n/2)$
- (c) $x(n) = \left(\frac{\sin(\pi n/8)}{\pi n}\right)^2$

upsampling with $M=3$



downsampling with a factor of $M=3$

mult with anti-imaging LP



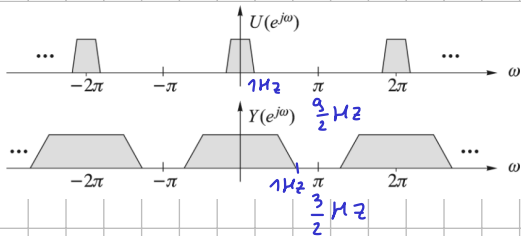
Downsampling: Re-sample a signal $x(n)$ that has a sampling rate of f_s with a new sample rate of $\frac{f_s}{M}$ } Downsampling factor

! Spectra repetitions at multiples of $\frac{f_s}{M}$

$$Y(e^{j\Omega'}) = \frac{1}{M} \sum_{k=0}^{M-1} X(e^{j(\Omega' - k2\pi)/M})$$

↳ Aliasing if sampling theorem is violated

↳ Anti-imaging filter (LP) before DS to avoid aliasing } decimation



e.g. $f_s = 9 \text{ Hz}$, $M=3 \rightsquigarrow \frac{f_s}{M} = 3 \text{ Hz}$

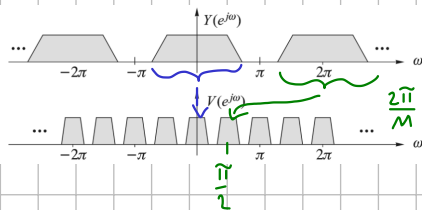
} spectrum looks stretched after DS

as f_s is lowered & π represents $\frac{f_s}{2}$

! only visual in Ω -domain

Upsampling: Insert zeros in-between sample values

↳ scaling of freq. axis by M

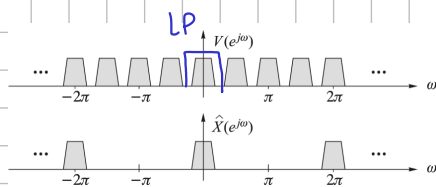


e.g. $M=4$

} compression of freq. axis

$$\frac{2\pi}{M} = \frac{2\pi}{4} = \frac{\pi}{2}$$

Anti-imaging & reconstruction:



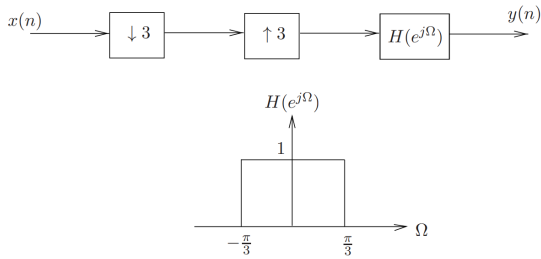
LP: rect in freq. \rightsquigarrow mult with

si in time \rightsquigarrow convolve with
↳ interpolate samples

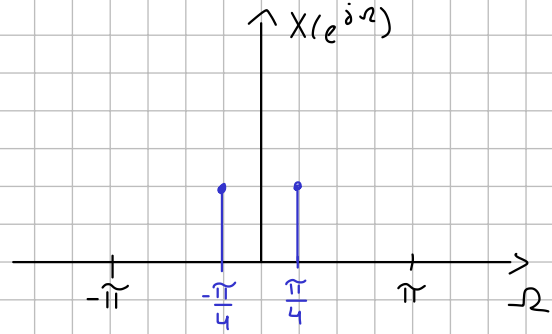
Problem 15 (Multirate Digital Signal Processing)

Consider the system shown in the figure. For each of the following input signals $x(n]$, indicate whether the output $y(n) = x(n)$.

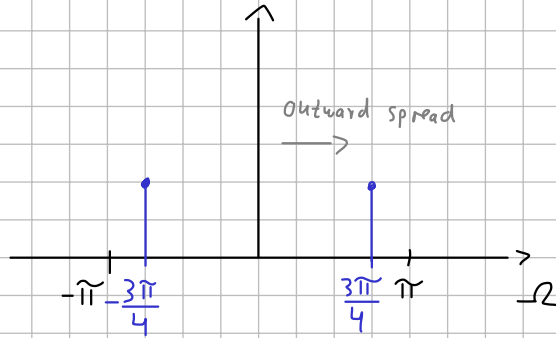
- (a) $x(n) = \cos(\pi n/4)$
- (b) $x(n) = \cos(\pi n/2)$
- (c) $x(n) = (\frac{\sin(\pi n/8)}{\pi n})^2$



a.) $X(n) = \cos(n \cdot \frac{\pi}{4})$

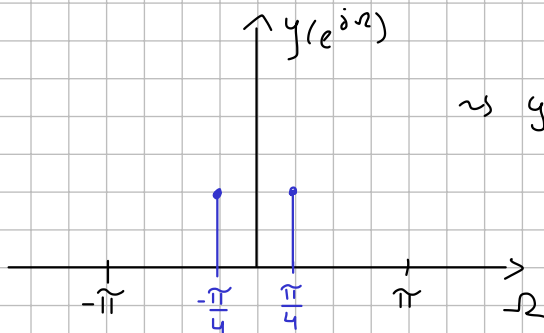
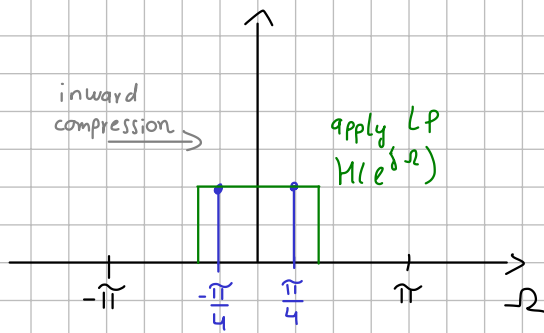


DS with $M=3$:



No aliasing from DS as
 max freq. $\frac{3\pi}{4} \leq \pi \Rightarrow \frac{fs}{2}$

US with $M=3$:

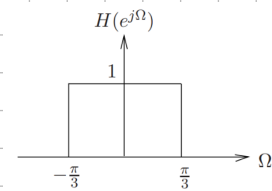


$\approx y(n) = x(n)$

b.) $x(n) = \cos(n \cdot \frac{\pi}{2})$

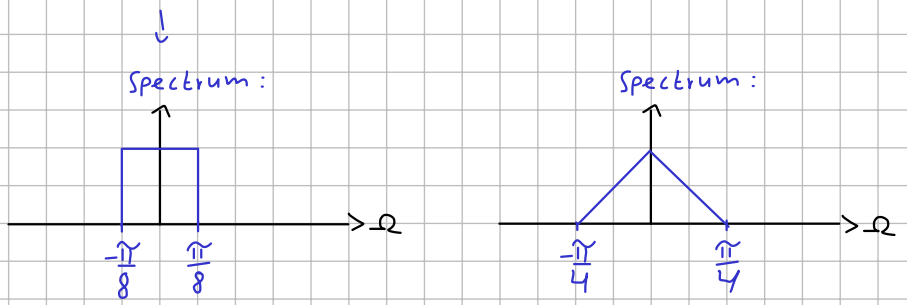
$\frac{\pi}{2} > \frac{\pi}{3}$ component gets filtered out by $H(e^{j\Omega})$

$y(n) \neq x(n)$

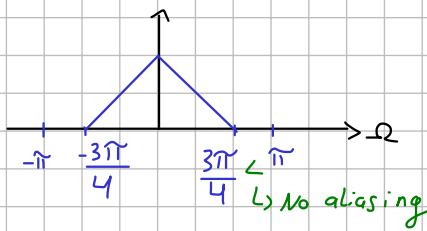


$$c.) X(n) = \left(\frac{\sin(n \cdot \frac{\pi}{8})}{n \cdot \pi} \right)^2 = \frac{1}{8^2} \left(\frac{\sin(n \cdot \frac{\pi}{8})}{n \cdot \frac{\pi}{8}} \right)^2 = \frac{1}{64} \cdot \text{sinc}^2(n \cdot \frac{\pi}{8})$$

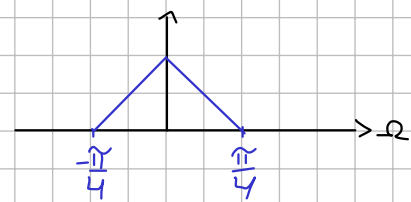
convolution of spectra due to squaring



after DS:



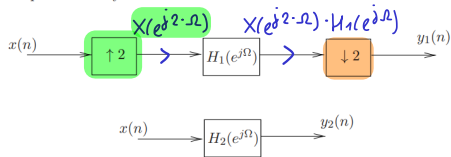
after US:



anti-aliasing: $\frac{\pi}{4} < \frac{\pi}{3} \rightarrow$ spectrum passes LP & $y(n) = x(n)$

Problem 16 (Multirate Digital Signal Processing)

Consider the systems shown in the figure. Suppose that $H_1(e^{j\Omega})$ is fixed and known. Find $H_2(e^{j\Omega})$, the frequency response of an LTI system, such that $y_2(n) = y_1(n)$, if the inputs to the systems are the same.



$y_1(e^{j\Omega})$ is $X(e^{j2\Omega}) \cdot H_1(e^{j\Omega})$ downsampled by $M=2$

$$Y(e^{j\Omega}) = \frac{1}{M} \sum_{k=0}^{M-1} X(e^{j(\Omega - k2\pi)/M})$$

$$y_1(e^{j\Omega}) = \frac{1}{2} \cdot [X(e^{j2\Omega}) \cdot H_1(e^{j\Omega/2}) + X(e^{j2(\Omega - 2\pi)}) \cdot H_1(e^{j(\Omega - 2\pi)/2})]$$

$$= \frac{1}{2} \cdot [X(e^{j\Omega}) \cdot H_1(e^{j\Omega/2}) + X(e^{j(\Omega - 2\pi)}) \cdot H_1(e^{j(\frac{\Omega}{2} - \pi)})]$$

$$= X(e^{j\Omega}) \cdot \frac{1}{2} \cdot [H_1(e^{j\Omega/2}) - H_1(e^{j(\frac{\Omega}{2} - \pi)})]$$

$$= X(e^{j\Omega}) \cdot H_2(e^{j\Omega}) \quad H_2(e^{j\Omega}), \text{ freq. response of equivalent system}$$