

Problem 13 (Digital IIR Filter Design)

The system function of a discrete-time system is

$$H(z) = \frac{2}{1 - e^{-0.2}z^{-1}} - \frac{1}{1 - e^{-0.4}z^{-1}}$$

- (a) Assume that this discrete-time filter was designed by the **impulse invariance method** with $T = 2$, i.e. $h_i = h_a(iT)$, where $h_a(t)$ is real. Find the system function $H_a(s)$ of a continuous-time filter that could have been the basis for the design. Is your answer unique? If not, find another system function $H_a(s)$.

Impulse invariance method:

Convert an **analog filter** designed in the analog domain (s -domain)
to a **digital filter** (z -domain)

analog filter impulse response: $h_a(t) \rightarrow$ sample with $f_s = \frac{1}{T}$ at $h_a(nT) = h_n(n)$

Laplace transform

$$h_a(t) = \begin{cases} \sum_{i=0}^{N-1} A_i \cdot e^{s_{\infty,i} \cdot t}, & t \geq 0 \\ 0, & \text{else} \end{cases}$$

$$H_a(s) = \sum_{i=0}^{N-1} \frac{A_i}{s - s_{\infty,i}}$$

$\{ \frac{A_i}{s - s_{\infty,i}} \}$ partial fraction expansion term (to get distinct poles)
distinct poles

z -transform

$$h_n(n) = h_a(nT) = \sum_{i=0}^{N-1} A_i \cdot e^{s_{\infty,i} \cdot nT}$$

$$H(z) = \sum_{i=0}^{N-1} \frac{A_i}{1 - e^{s_{\infty,i} \cdot T} z^{-1}}$$

$$\frac{1}{s - s_{\infty,i}} \longleftrightarrow \frac{1}{1 - e^{s_{\infty,i} \cdot T} z^{-1}}$$

$$z_{\infty,i} = e^{s_{\infty,i} \cdot T}$$

Poles of digital IIR-filter

Here: $H(z) = \frac{2}{1 - \underbrace{e^{-0.2}}_{z_{\infty,0}} z^{-1}} - \frac{1}{1 - \underbrace{e^{-0.4}}_{z_{\infty,1}} z^{-1}}$

$$z_{\infty,i} = e^{s_{\infty,i} \cdot T}$$

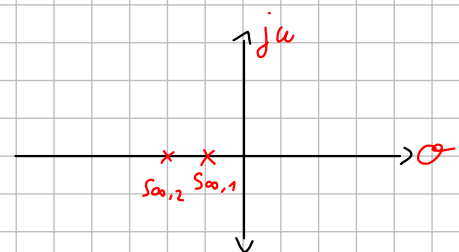
$$\hookrightarrow -0.2 = s_{\infty,0} \cdot \underbrace{T}_{=2}$$

$$s_{\infty,0} = \frac{-0.2}{2} = -0.1$$

$$s_{\infty,1} = -0.2$$

$$\hookrightarrow H_a(s) = \sum_{i=0}^{N-1} \frac{A_i}{s - s_{\infty,i}} = \frac{2}{s - (-0.1)} - \frac{1}{s - (-0.2)}$$

$$= \frac{2}{s + 0.1} - \frac{1}{s + 0.2}$$



2 distinct poles on σ -axis
 \hookrightarrow unique solution

- (b) Assume that $H(z)$ was obtained by the bilinear transform with $T = 2$. Find the system function $H_a(s)$ that could have been the basis for the design. Is your answer unique? If not, find another $H_a(s)$.

Bilinear transform: Algebraic transform

from s -to z -domain

$$s = \frac{2}{T} \left(\frac{1-z^{-1}}{1+z^{-1}} \right), \quad z = \frac{1 + \frac{T}{2} \cdot s}{1 - \frac{T}{2} \cdot s}$$

$$H(z) = H_a \left[s = \frac{2}{T} \left(\frac{1-z^{-1}}{1+z^{-1}} \right) \right]$$

$$H_a(s) = H \left[z = \frac{1 + \frac{T}{2} \cdot s}{1 - \frac{T}{2} \cdot s} \right]$$

$$\begin{aligned} \hookrightarrow H_a(s) &= \frac{2}{1 - e^{-0,2} \left[\frac{1 + \frac{T}{2} \cdot s}{1 - \frac{T}{2} \cdot s} \right]^{-1}} - \frac{1}{1 - e^{-0,4} \left[\frac{1 + \frac{T}{2} \cdot s}{1 - \frac{T}{2} \cdot s} \right]^{-1}} \\ &= \frac{2}{1 - e^{-0,2} \left(\frac{1-s}{1+s} \right)} - \frac{1}{1 - e^{-0,4} \left(\frac{1-s}{1+s} \right)} \end{aligned}$$

$T=2 \Rightarrow \frac{T}{2}=1$

$$\cdot \frac{1+s}{1+s} \quad = \quad \frac{2(1+s)}{(1+s) - e^{-0,2} \cdot (1-s)} - \frac{1+s}{(1+s) - e^{-0,4} \cdot (1-s)}$$

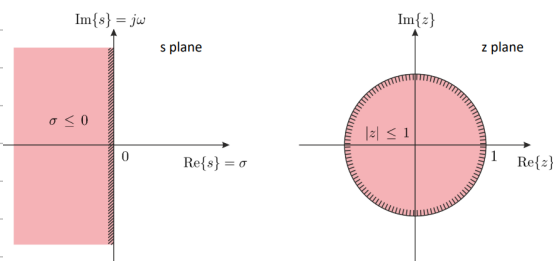
factorize $(1+e^{-0,2})$

to get $s + \dots$

$$= \frac{2(1+s)}{s(1+e^{-0,2}) + (1-e^{-0,2})} - \frac{1+s}{s(1+e^{-0,4}) + (1-e^{-0,4})}$$

$$= \underbrace{\frac{2}{1+e^{-0,2}}}_{\text{scalar factor}} \cdot \underbrace{\frac{s+1}{s + \frac{1-e^{-0,2}}{1+e^{-0,2}}}}_{\text{term with } s} - \frac{1}{1+e^{-0,4}} \cdot \frac{s+1}{s + \frac{1-e^{-0,4}}{1+e^{-0,4}}}$$

Due to the property of the unique transform of the bilinear transform, the representation is unique



Bilinear transform is unique!

$j\omega$ -axis maps onto unit circle

Problem 14 (Digital IIR Filter Design)

A discrete-time lowpass filter is to be designed by applying the impulse invariance method to a continuous-time Butterworth filter having magnitude-squared function

$$|H(j\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_{cut}}\right)^{2N}}$$

The specifications for the discrete-time signal are

$$\begin{aligned} 0.89125 \leq |H(e^{j\Omega})| \leq 1, & \quad 0 \leq |\Omega| \leq 0.2\pi, \\ |H(e^{j\Omega})| \leq 0.17783, & \quad 0.3\pi \leq |\Omega| \leq \pi. \end{aligned}$$

Assume that aliasing will not be a problem, i.e., design the continuous-time Butterworth filter to meet passband and stopband specifications as determined by the discrete-time filter.

- (a) Sketch the tolerance bounds on the magnitude of the frequency response, $|H(j\omega)|$, of the continuous-time Butterworth filter such that after application of the impulse invariance method, the resulting discrete-time filter will satisfy the given design specifications. Do not assume that $T = 1$.

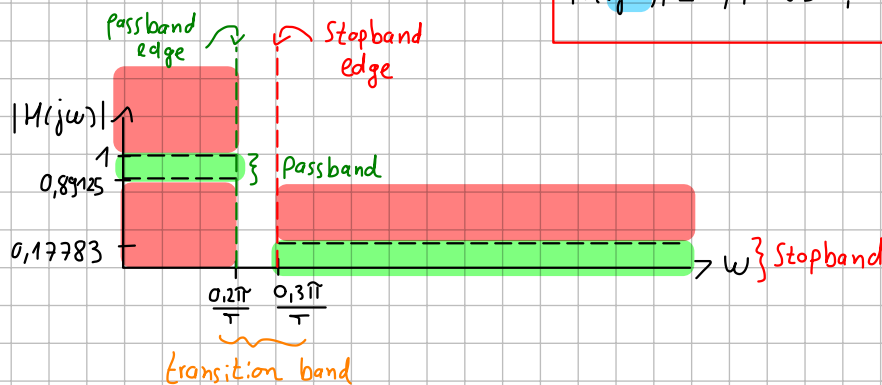
Filter specifications

For discrete-time signal \downarrow DTFT $\Omega \rightarrow \omega$ continuous-time Butterworth filter $\omega \rightarrow \omega$

$$\begin{aligned} 0.89125 \leq |H(e^{j\Omega})| \leq 1, & \quad 0 \leq |\Omega| \leq 0.2\pi, \\ |H(e^{j\Omega})| \leq 0.17783, & \quad 0.3\pi \leq |\Omega| \leq \pi. \end{aligned}$$

$$\begin{aligned} \Omega &= \omega T = \frac{\omega}{f_s} \\ \omega &= \frac{\Omega}{T} = \Omega \cdot f_s \end{aligned}$$

$$\begin{aligned} 0.89125 \leq |H(j\omega)| \leq 1, & \quad 0 \leq |\omega| \leq \frac{0.2\pi}{T} \\ |H(j\omega)| \leq 0.17783, & \quad \frac{0.3\pi}{T} \leq |\omega| \leq \frac{\pi}{T} \end{aligned}$$

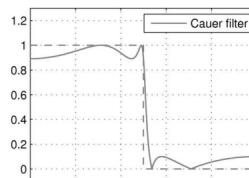
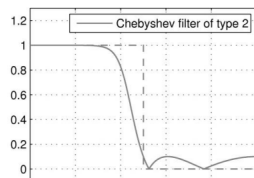
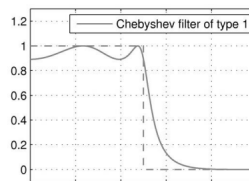
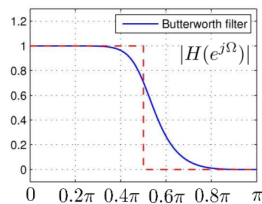


Butterworth filters

Lowpass Butterworth filters are allpole-filters characterized by the squared magnitude frequency response

$$|H(\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_{cut}}\right)^{2N}}$$

N is the order of the filter,
 ω_{cut} is the -3 dB frequency (cut-off frequency).



- (b) Determine the integer order N and the quantity $\omega_{cut}T$ such that the continuous-time Butterworth filter exactly meets the specifications determined in part (a) at the passband edge.

At Stopband edge: $\frac{1}{1 + \left(\frac{\omega_{stop}}{\omega_{cut}}\right)^{2N}} = \delta_2^2 \rightarrow N = \frac{\log_{10}([1/\delta_2^2] - 1)}{2 \log_{10}(\omega_{stop}/\omega_{cut})}$

Stopband edge: $|H(j0,3\pi/T)|^2 \stackrel{!}{=} 0,17783^2$

$$a = \frac{1}{1 + \left(\frac{0,3\pi}{\omega_c T}\right)^{2N}}$$

$$a = \frac{1}{1 + \left(\frac{b}{c}\right)^{2N}}$$

$$a = \frac{1}{1 + \left(\frac{b}{c}\right)^{2N}}$$

$$\frac{1}{a} = 1 + \left(\frac{b}{c}\right)^{2N}$$

$$\log_{10}\left(\frac{1}{a} - 1\right) = 2 \cdot N \cdot \log_{10}(b/c)$$

$$N = \frac{\log_{10}\left(\frac{1}{a} - 1\right)}{2 \cdot \log_{10}(b/c)} = \frac{\log_{10}\left(\frac{1}{0,17783^2} - 1\right)}{2 \cdot \log_{10}\left(\frac{0,3\pi}{\omega_c T}\right)}$$

passband edge: $|M(j0,2\pi/T)|^2 \stackrel{!}{=} 0,89125^2 = \frac{1}{1 + \left(\frac{0,2\pi}{\omega_c T}\right)^{2N}}$

$$\frac{\omega}{\omega_c} = \frac{e}{c}$$

$$d = \frac{1}{1 + \left(\frac{e}{c}\right)^{2N}}$$

$$d^{-1} - 1 = \left(\frac{e}{c}\right)^{2N}$$

$$\log_{10}(d^{-1} - 1) = 2N \cdot (\log_{10} e - \log_{10} c)$$

$$\log_{10} c = \log_{10} e - \frac{\log_{10}(d^{-1} - 1)}{2N}$$

$$c = 10 \left(\log_{10} e - \frac{\log_{10}(d^{-1} - 1)}{2N} \right)$$

III.) $c = \omega_c T = 10 \left(\log_{10}(0,2\pi) - \frac{\log_{10}\left(\frac{1}{0,89125^2} - 1\right)}{2N} \right)$

↳ cut-off freq. specification of cont. time filter at passband edge

→ solve system of equations I.) & II.) for N & $\omega_c \cdot T$
2 unknowns

↳ $\omega_c \cdot T = 0,70474$

$N \approx 5,88$

↳ round up to next integer

↳ $N = 6$

↳ insert into III.)

↳ $\omega_c \cdot T = 0,7032$ for $N = 6$

fulfills our filter specifications
at the passband edge